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Thus, $\alpha_1^2 + \alpha_2^2 + \alpha_3^2 = 1$, so that a unit vector in the direction of the axis of rotation is $n = \frac{\alpha_1 e_1 + \alpha_2 e_2 + \alpha_3 e_3}{\sqrt{\alpha_1^2 + \alpha_2^2 + \alpha_3^2}}$. Lai et al, Introduction to Continuum Mechanics. Copyright 2010, Elsevier Inc 2-9. 2.29 A rigid body undergoes a right hand rotation of angle θ about an axis which is in the direction of the unit vector n .

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Thus, $\alpha_{12} = \alpha_{21}$, so that a unit vector in the direction of the axis of rotation is $n = \frac{e_1 e_2 - e_2 e_1}{\sqrt{2}}$. Lai et al, Introduction to Continuum Mechanics. Copyright 2010, Elsevier Inc 2-9. 2.29 A rigid body undergoes a right hand rotation of angle θ about an axis which is in the direction of the unit vector n .

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